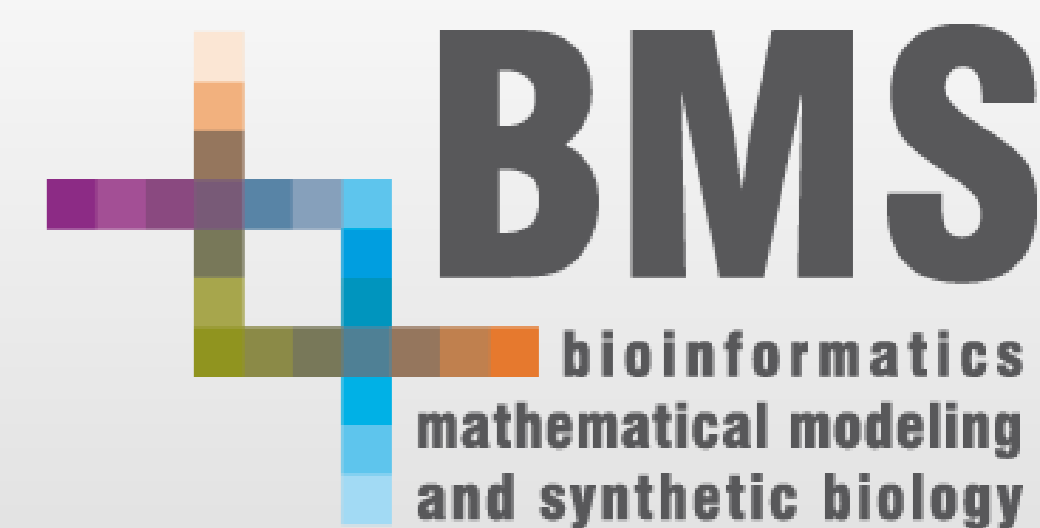


# Model-Informed Reinforcement Learning for precision dosing of Carboplatin

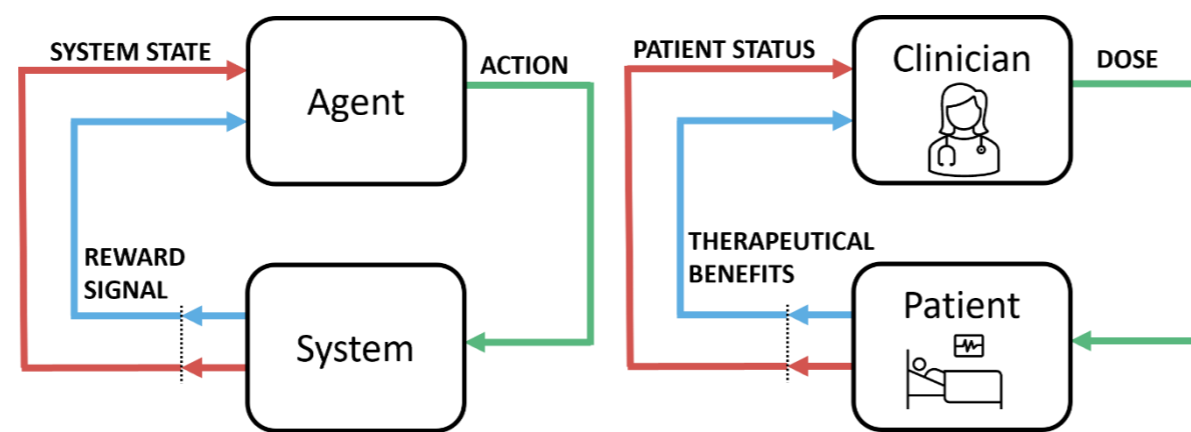
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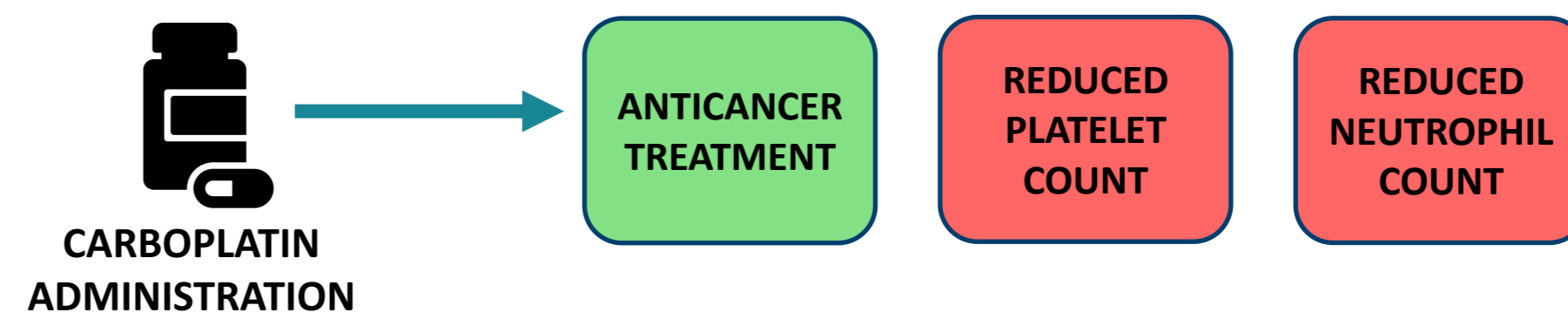
## BACKGROUND:

- Precision dosing personalizes drug therapy to maximize efficacy while minimizing toxicity [1,2].
- Model-Informed Precision Dosing (MIPD) relies on PK-PD models and Bayesian estimation approaches to create patient-specific digital twins and simulate the patient therapeutic responses [3, 4, 5].
- Exploring multiple dosing strategies through MIPD may become computationally demanding.
- Reinforcement Learning (RL) is increasingly used to identify optimal adaptive dosing strategies through sequential decision-making algorithms [6, 7].



## AIM:

Investigate the potential of a combined MIPD + RL (specifically Q-Learning, QL [8]) framework for the optimization of carboplatin dosing in lung cancer patients.

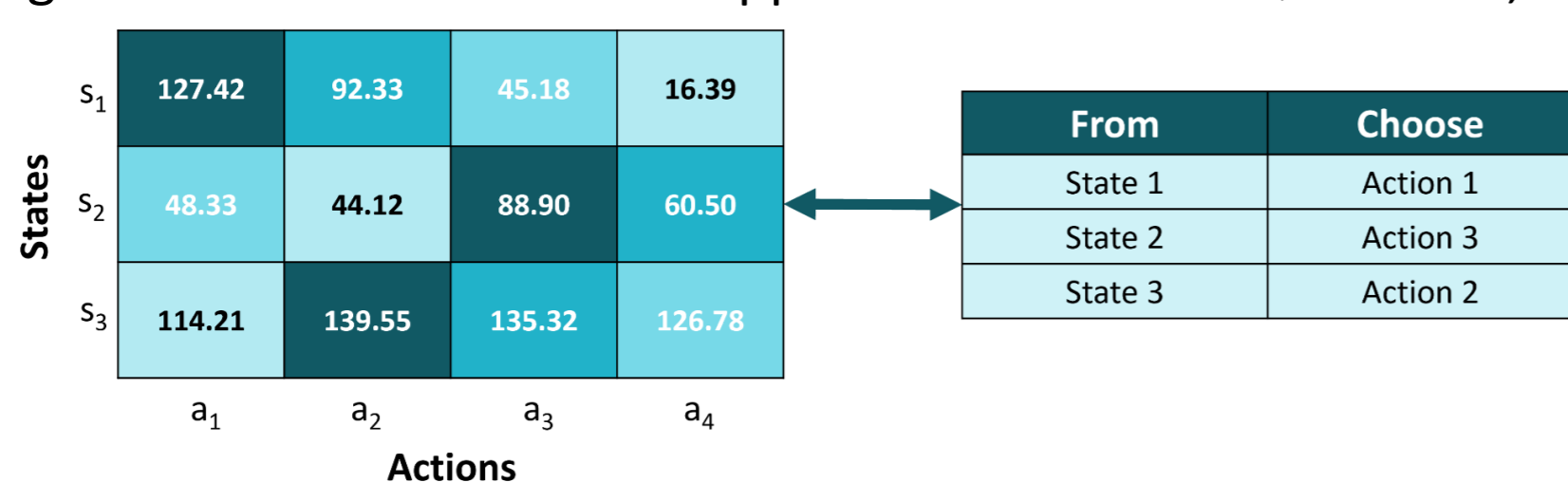


## Therapeutic objective:

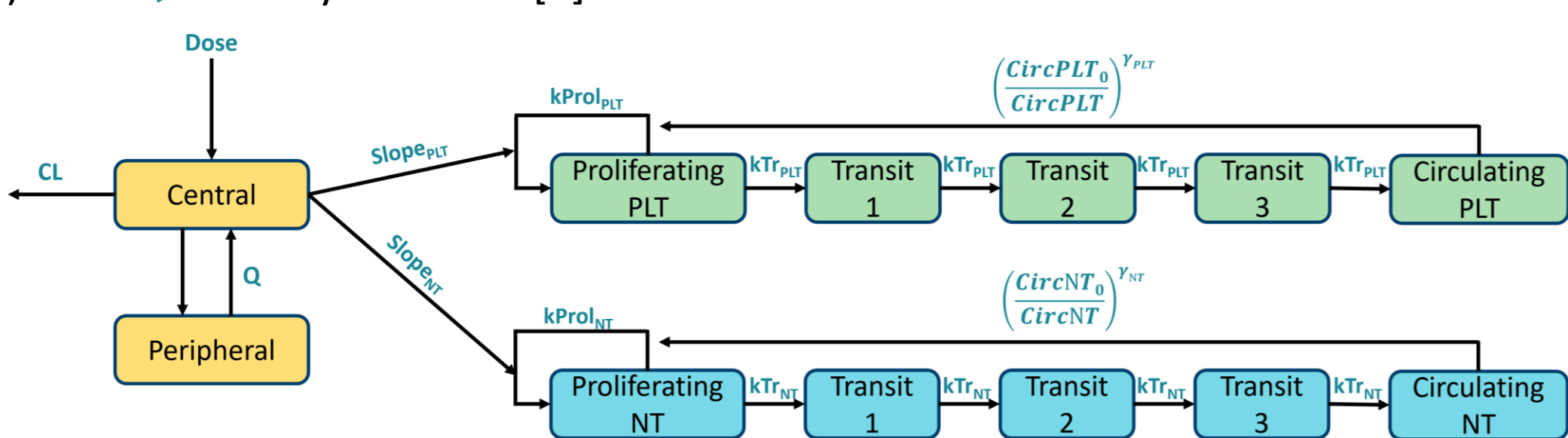
Maximize the administered dose while preventing severe myelosuppression of platelets (PLT) and neutrophils (NT).

## MATERIALS AND METHODS:

**Q-Learning:** RL algorithm based on a tabular approximation of the Q-function, called Q-matrix

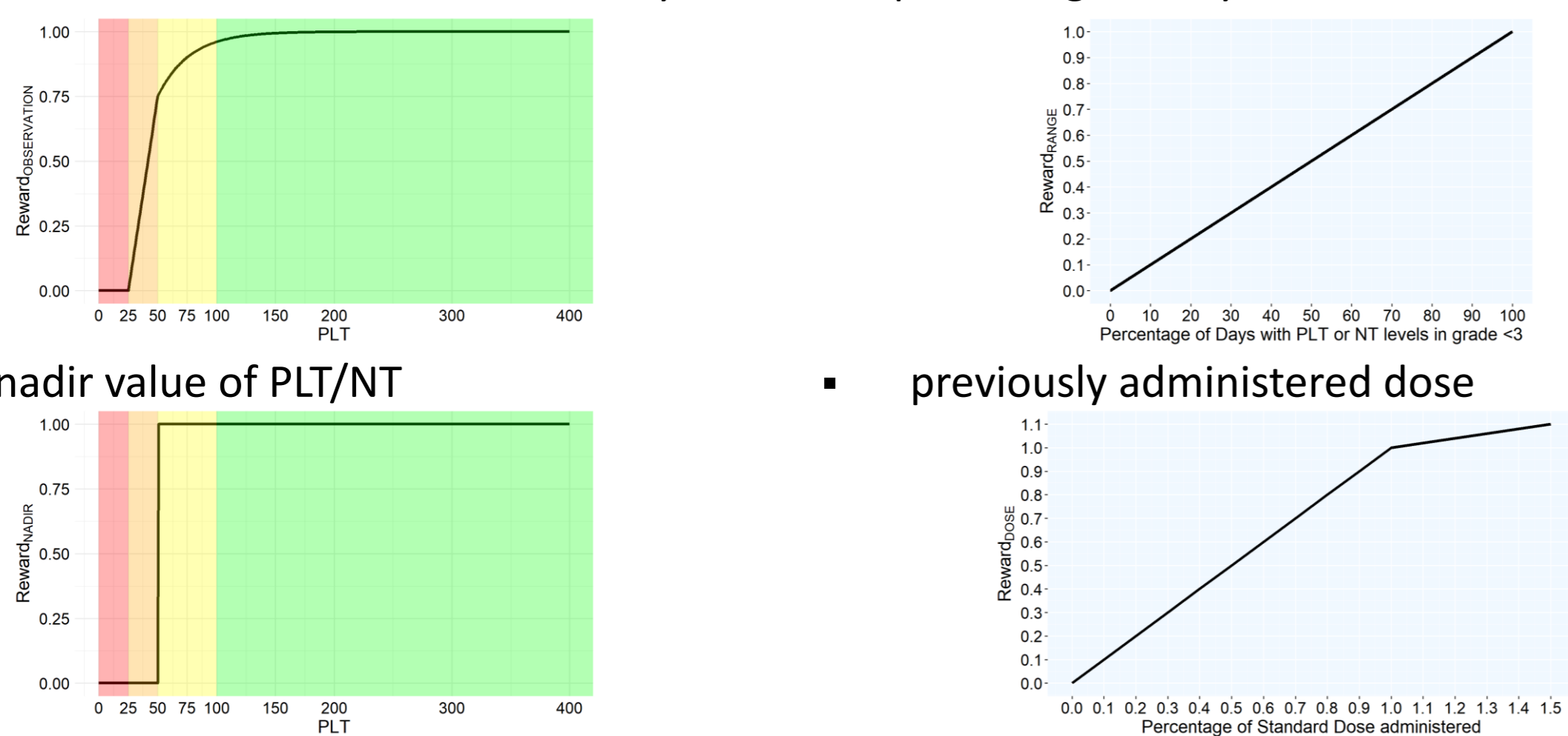


- PK-PD model** of carboplatin-induced myelosuppression in platelets (PLT) and neutrophils (NT) — already available [9].

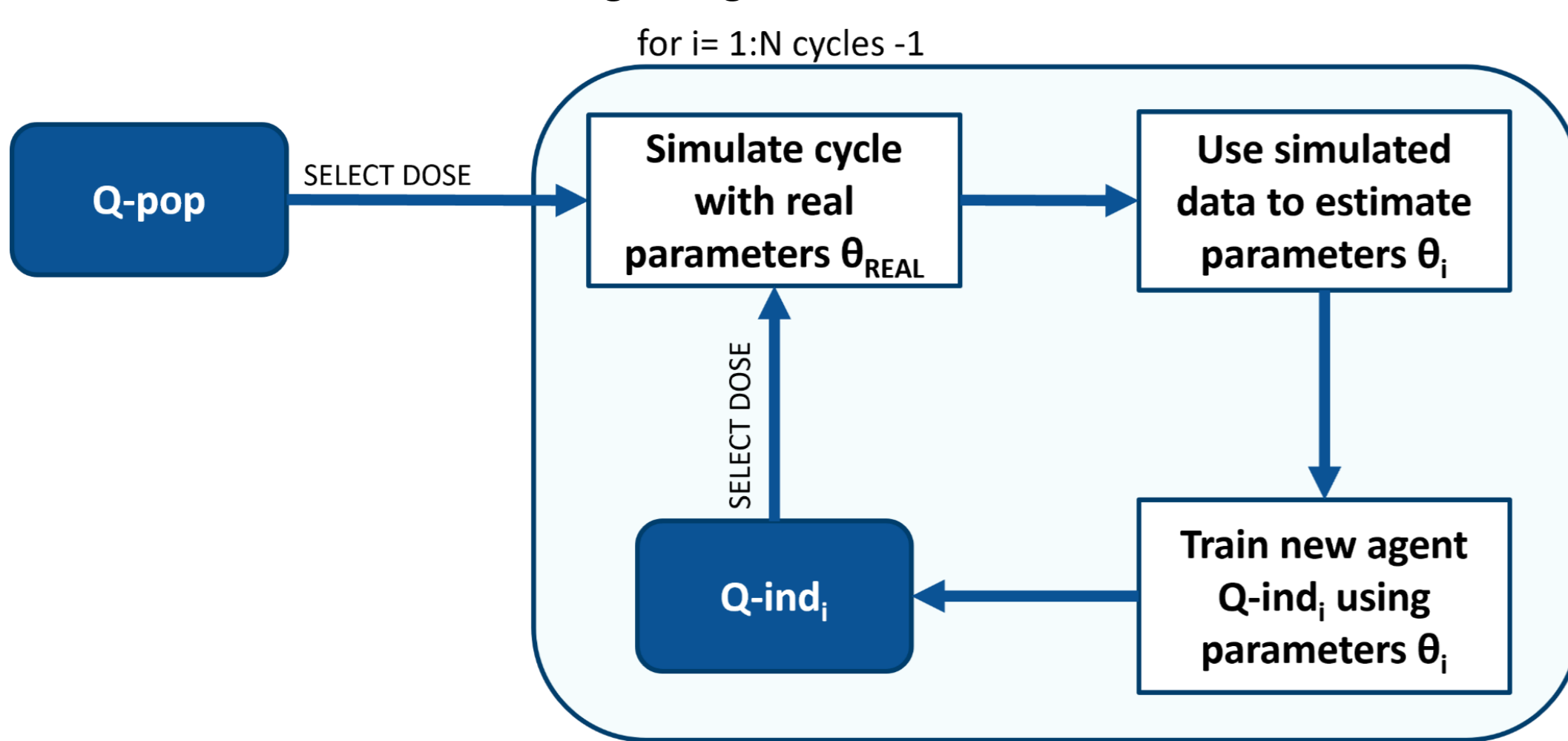


- Actions** — expressed as fractions of the standard individual carboplatin dose: [0, 0.5, 0.8, 0.9, 1, 1.1, 1.2, 1.5] x standard dose.
- System States** — maximum toxicity level observed in PLT and NT at the end of the cycle, along with the previously administered dose.
- Reward function** — defined by:

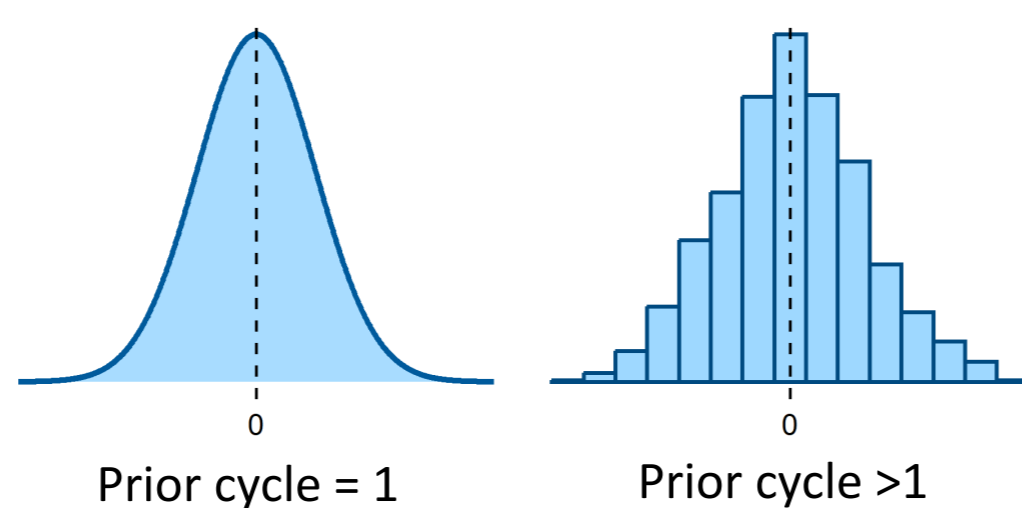
- value of PLT/NT at the end of the cycle
- percentage of days without PLT/NT toxicity
- nadir value of PLT/NT
- previously administered dose



**Bayesian framework:** implemented to simulate real clinical conditions, where individual parameters are not available at the beginning of the treatment.



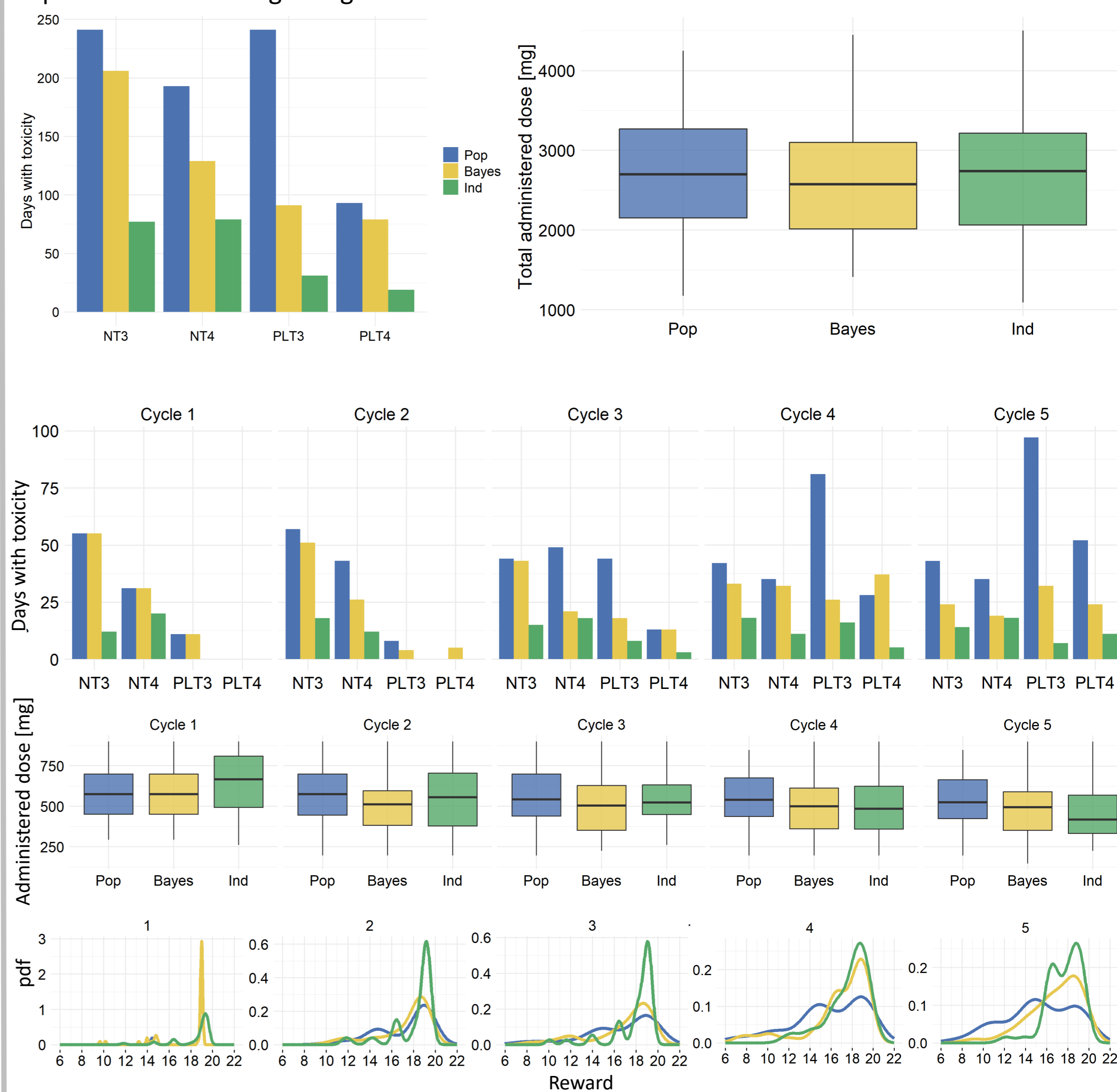
**To estimate individual parameters:** MCMC algorithm where in the first cycle, the population prior was used, while in the subsequent cycles, an empirical prior based on the samples obtained in the previous cycle was adopted.



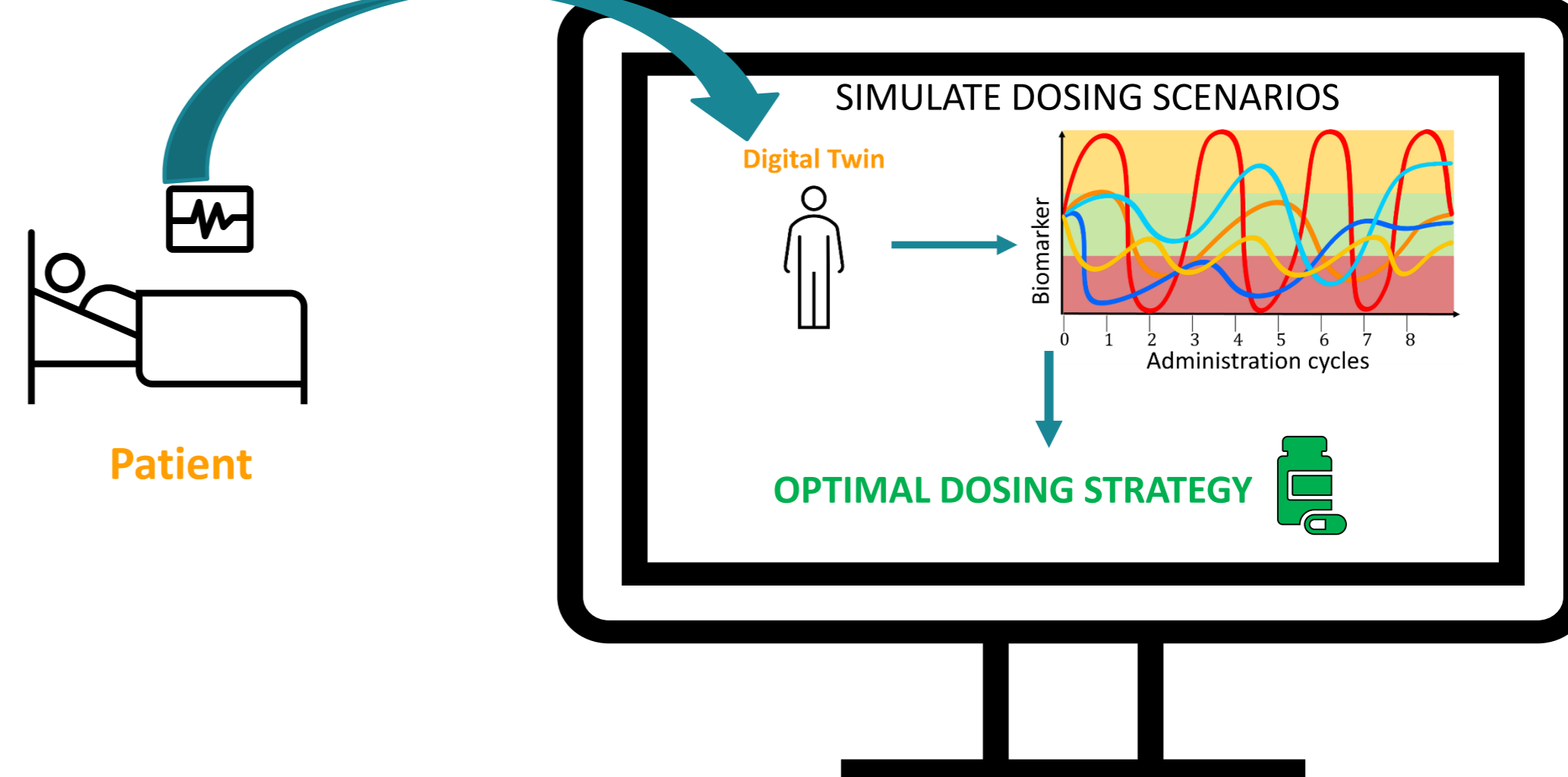
## RESULTS:

To test the proposed framework, a population of 41 virtual patients was created. For each patient, outcomes were evaluated using three different Q-learning agents:

- Population agent:** trained on a large external virtual population. It represents a general protocol intended to work across the entire population, but it is not optimized for any specific patient.
- Bayesian agent:** trained using the proposed framework. It aims to replicate a realistic clinical scenario in which patient-specific parameters are not known a priori but are progressively inferred.
- Individual agent:** patient-specific agent trained directly using the true parameters of each patient from the beginning.



**Clinician oriented GUI:** a graphical user interface was developed through which clinicians can simulate different scenarios and observe their potential effects on the patient. From the application, it is possible to input patient data, obtain a digital twin by identifying individual parameters, and simulate both the recommendation provided by the QL algorithm and any alternative decision made by the clinician. The GUI was implemented in Python using the library PyQt6.



**CONCLUSIONS:** The proposed framework shows that the Bayesian agent outperforms the population protocol, but, as expected, it performs worse than the individual agent, which represents an unreachable benchmark. This supports the potential clinical application of the framework, further facilitated by the development of a GUI that enables easy use by clinicians.

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